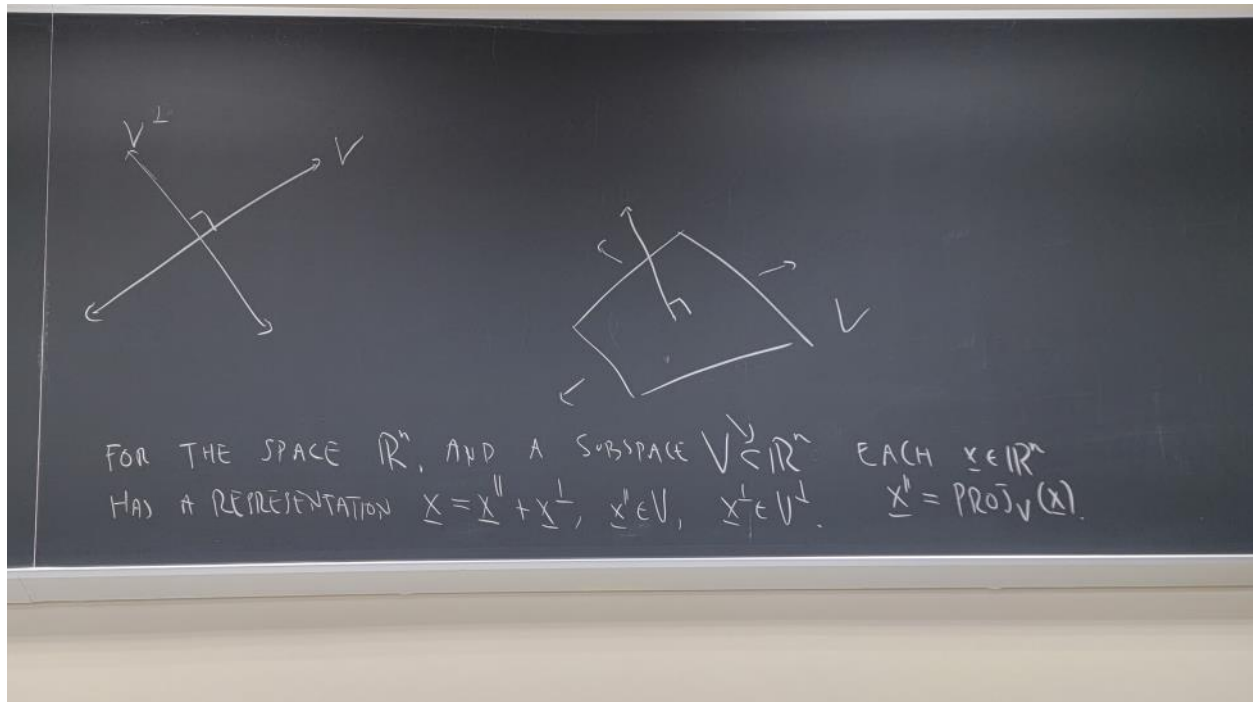
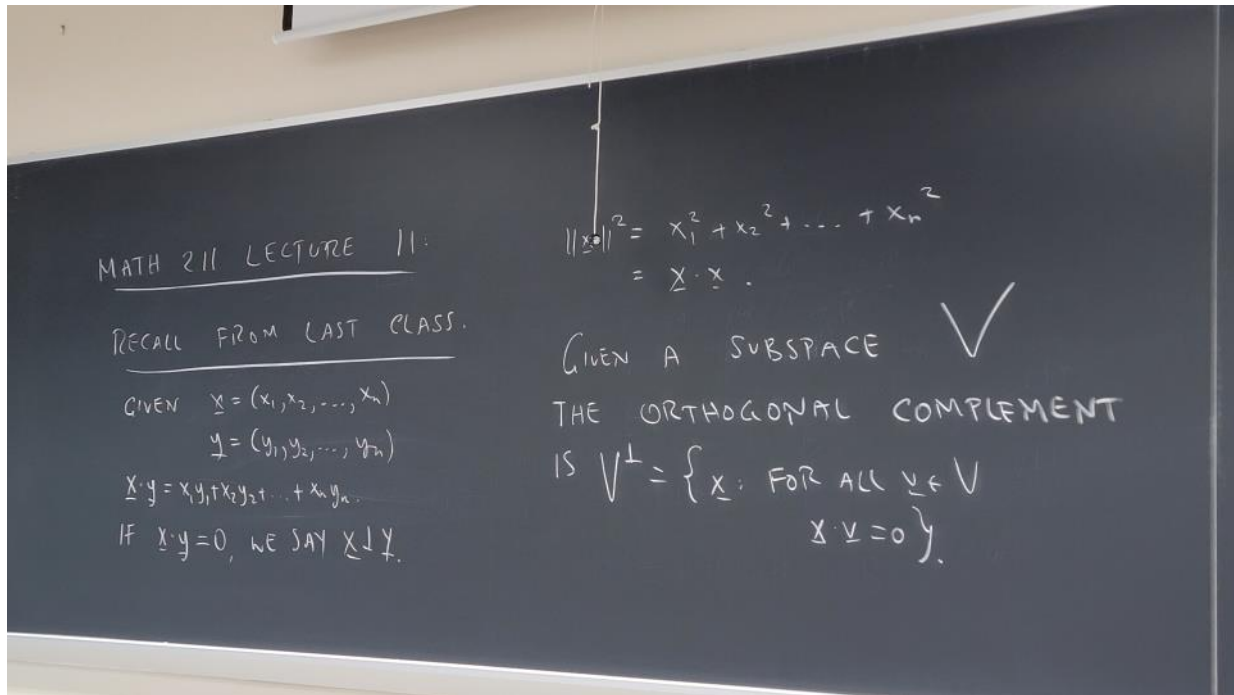
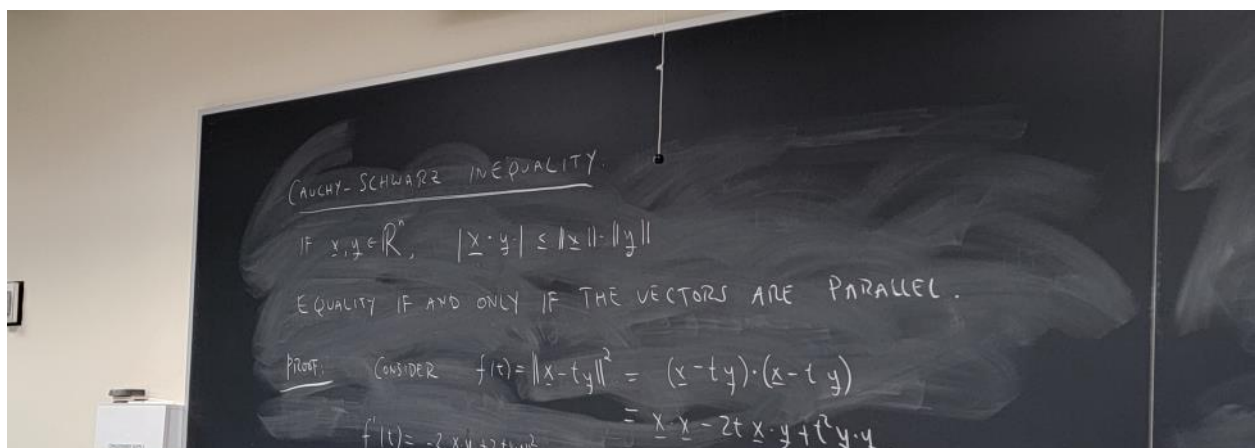
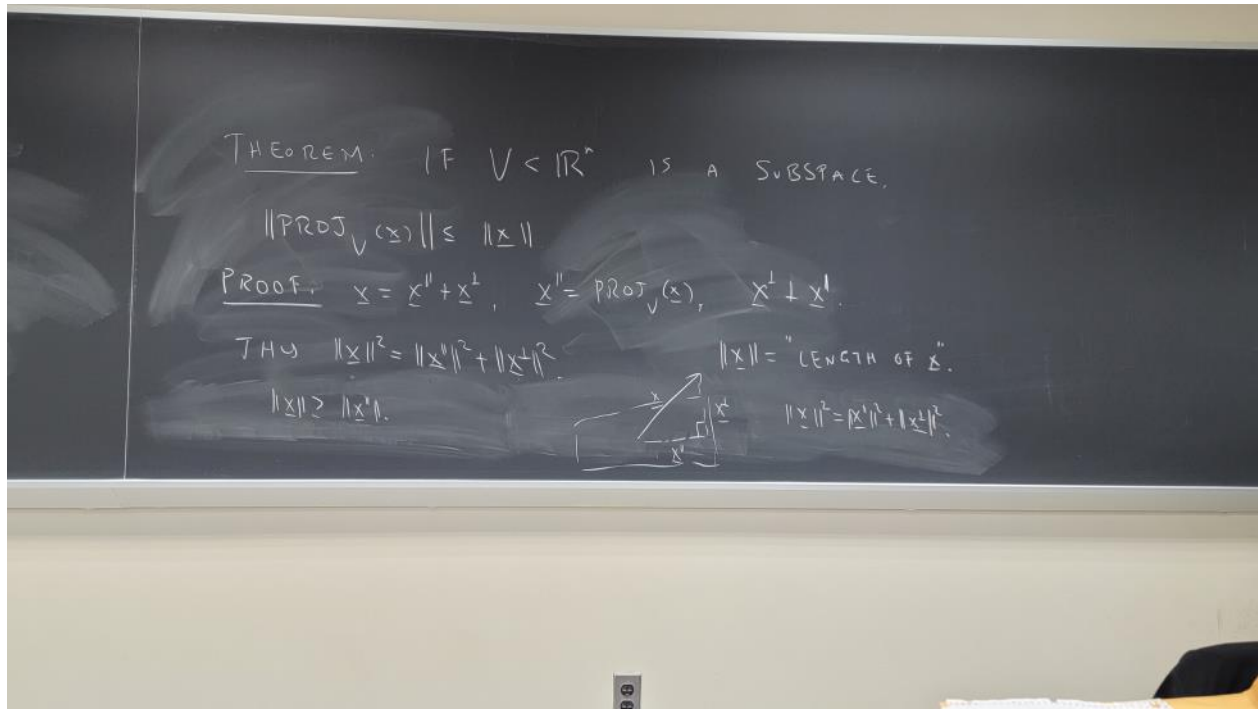
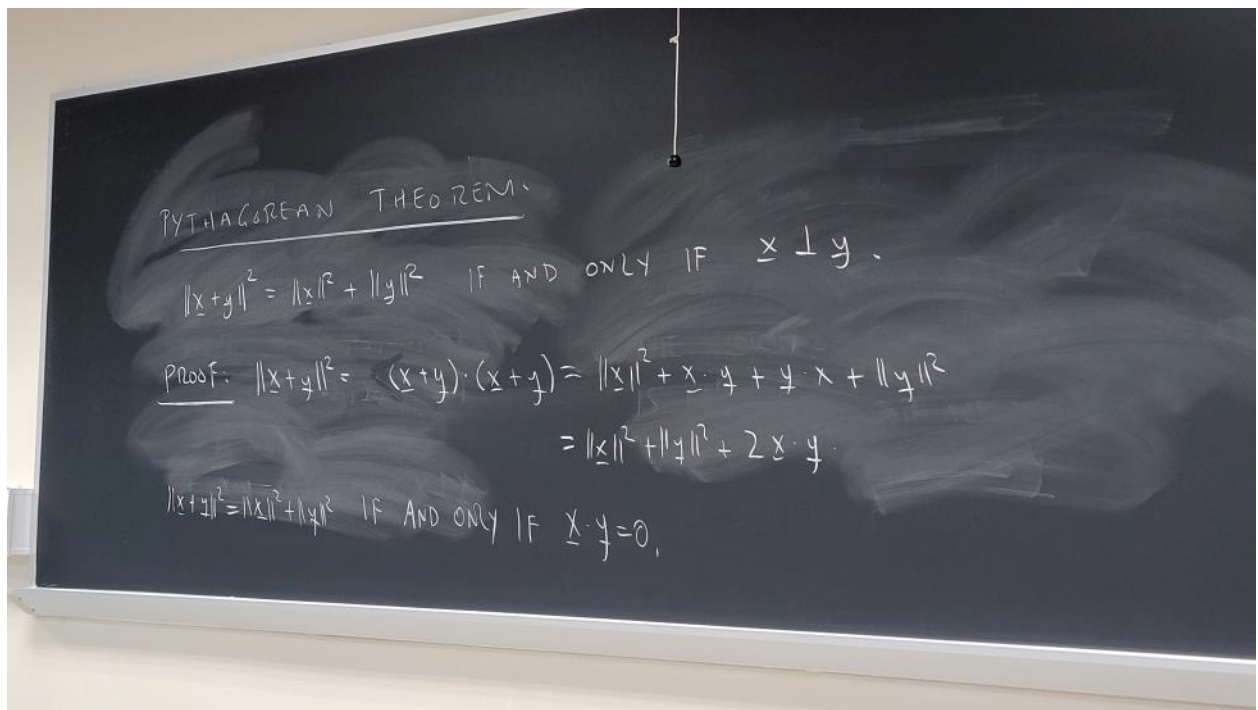


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Thursday, March 9, 2023 3:32 PM





CAUCHY-SCHWARZ INEQUALITY.

$$\text{IF } x, y \in \mathbb{R}^n, \quad |x \cdot y| \leq \|x\| \cdot \|y\|$$

EQUALITY IF AND ONLY IF THE VECTORS ARE PARALLEL.

PROOF. CONSIDER $f(t) = \|x - ty\|^2 = (x - ty) \cdot (x - ty)$
 $f(t) = -2x \cdot y + t^2 \|y\|^2 = \|x\|^2 - 2t x \cdot y + t^2 \|y\|^2$

THE LENGTH IS MINIMIZED IF

$$x \cdot y = t \|y\|^2$$

ASSUME $y \neq 0$, SINCE CLAIM HOLDS IF $y = 0$.

$$t = \frac{x \cdot y}{\|y\|^2}$$

$$0 \leq \|x\|^2 - 2t x \cdot y + t^2 \|y\|^2 = \|x\|^2 - \frac{(x \cdot y)^2}{\|y\|^2} \Rightarrow |x \cdot y|^2 \leq \|x\|^2 \|y\|^2$$

EQUALITY IF $x - ty = 0 \Rightarrow$ PARALLEL. \square

GEOMETRIC INTERPRETATION.

GIVEN VECTORS $\underline{x}, \underline{y}$, BOTH NON-ZERO, DEFINE THE ANGLE BETWEEN THEM TO BE

$$\cos \theta = \frac{\underline{x} \cdot \underline{y}}{\|\underline{x}\| \|\underline{y}\|}, \quad \theta = \text{ANGLE.}$$

THIS DEFINES A NOTION OF ANGLE IN \mathbb{R}^n .

IN \mathbb{R}^2



$$|\cos \theta| = |\text{PROJ}_{\hat{\underline{x}}} \hat{\underline{y}}| = |\hat{\underline{x}} \cdot \hat{\underline{y}}|.$$

LENGTH OF VECTORS DOESN'T MATTER WHEN MEASURING ANGLE.

$$\hat{\underline{x}} = \frac{\underline{x}}{\|\underline{x}\|}, \quad \hat{\underline{y}} = \frac{\underline{y}}{\|\underline{y}\|}$$

$\hat{\underline{x}}, \hat{\underline{y}}$ LENGTH 1.

IN n DIMENSIONS, x, y SPAN A 2-DIMENSIONAL SUBSPACE OF \mathbb{R}^n . THE ANGLE IS THE SAME AS THE ANGLE MEASURED IN THIS SUBSPACE

EXAMPLE. WHAT ANGLE BETWEEN $x = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $y = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$$\cos \theta = \frac{x \cdot y}{\|x\| \|y\|} = \frac{1}{\|x\| \|y\|} = \frac{1}{2} \quad \|x\| = 1, \|y\| = \sqrt{4} = 2$$



$$r = \cos \theta = \frac{x \cdot y}{\|x\| \|y\|}$$

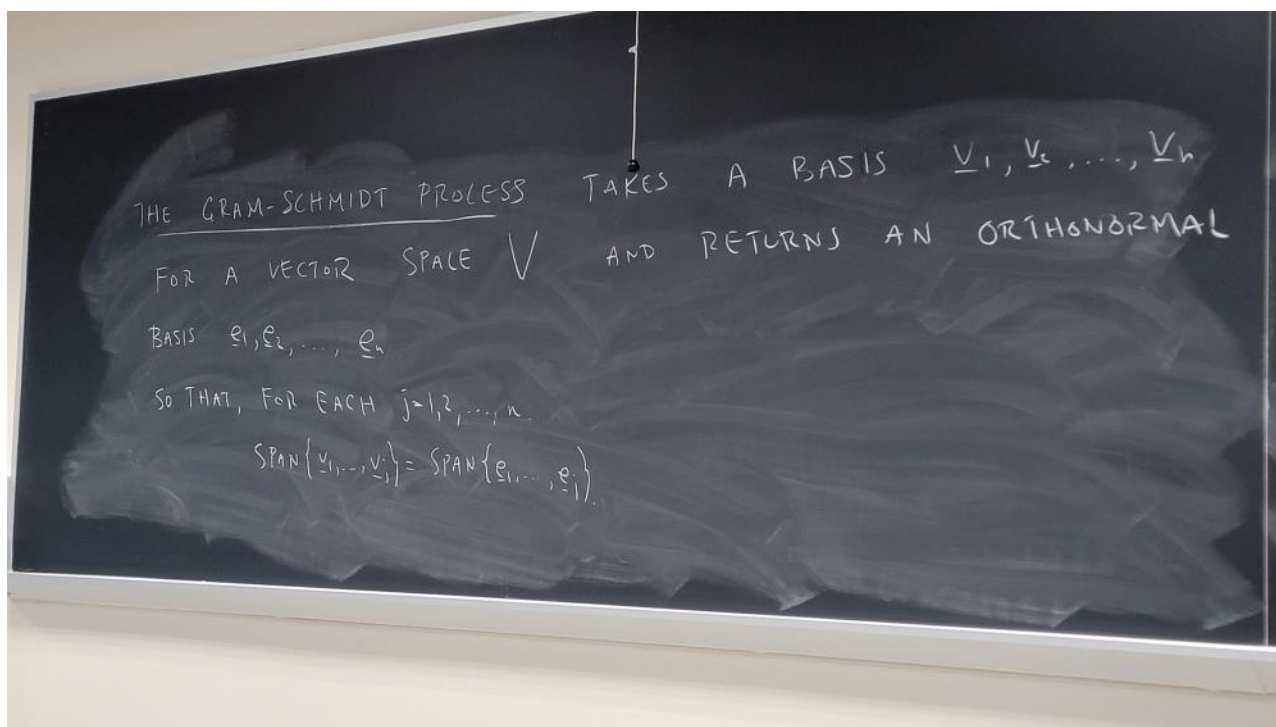
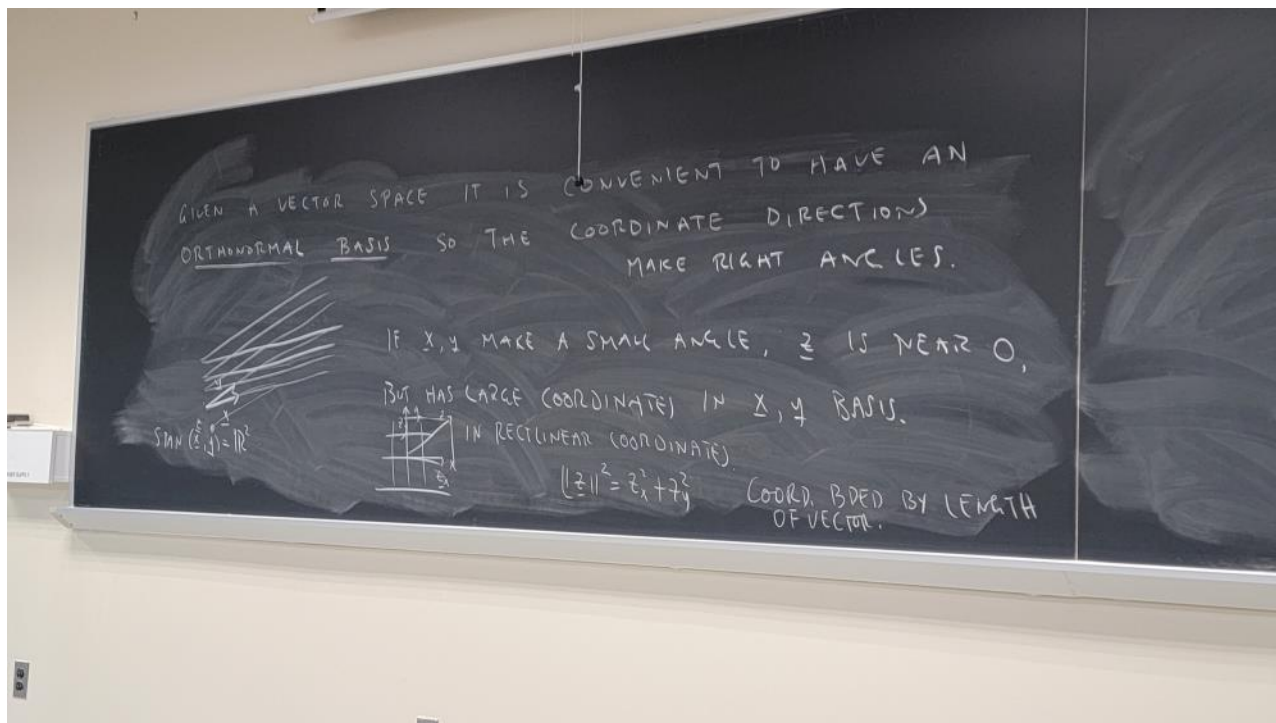
CORRELATION COEFFICIENT.

THE GRAM-SCHMIDT PROCESS

	HEIGHT FT	WEIGHT LBS
PERSON 1	5' 9"	155
PERSON 2	6' 4"	215
PERSON 3
PERSON 100	x	y

CORRELATION?

$$r = \frac{x \cdot y}{\|x\| \|y\|}$$



CONSTRUCTION.

$$\underline{e}_1 = \frac{\underline{v}_1}{\|\underline{v}_1\|} \quad \text{UNIT VECTOR IN DIRECTION } \underline{e}_1.$$

HAVING CONSTRUCTED $\underline{e}_1, \underline{e}_2, \dots, \underline{e}_j$

$$\underline{e}_{j+1} = \frac{\underline{v}_{j+1} - ((\underline{v}_{j+1} \cdot \underline{e}_1)\underline{e}_1 + \dots + (\underline{v}_{j+1} \cdot \underline{e}_j)\underline{e}_j)}{\|\underline{v}_{j+1} - ((\underline{v}_{j+1} \cdot \underline{e}_1)\underline{e}_1 + \dots + (\underline{v}_{j+1} \cdot \underline{e}_j)\underline{e}_j)\|}$$

*WRITE $\underline{v}_{j+1} = \underline{v}_{j+1}^{\parallel} + \underline{v}_{j+1}^{\perp}$

$$\underline{v}_{j+1}^{\parallel} = \text{PROJ}_{\text{SPAN}\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_j\}} \underline{v}_{j+1}$$
$$\underline{e}_{j+1} = \frac{\underline{v}_{j+1}^{\perp}}{\|\underline{v}_{j+1}^{\perp}\|} \quad \text{A UNIT LENGTH.}$$



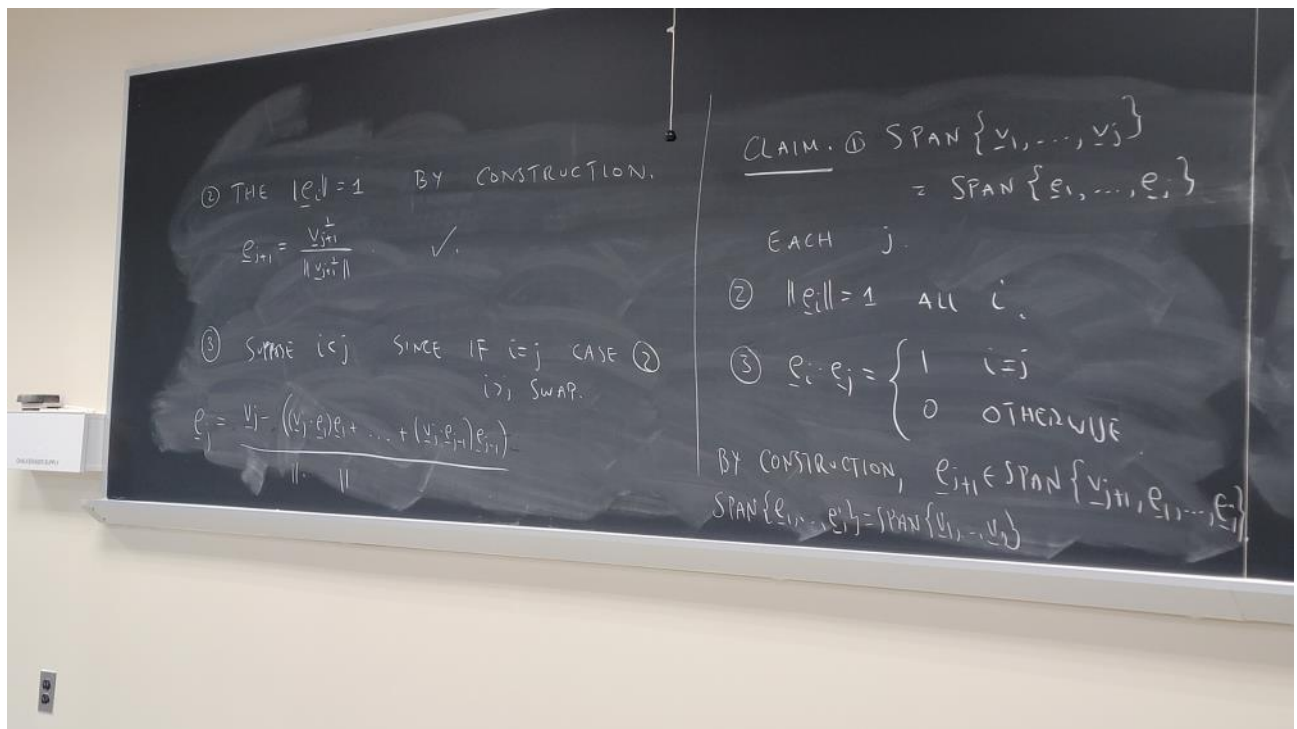
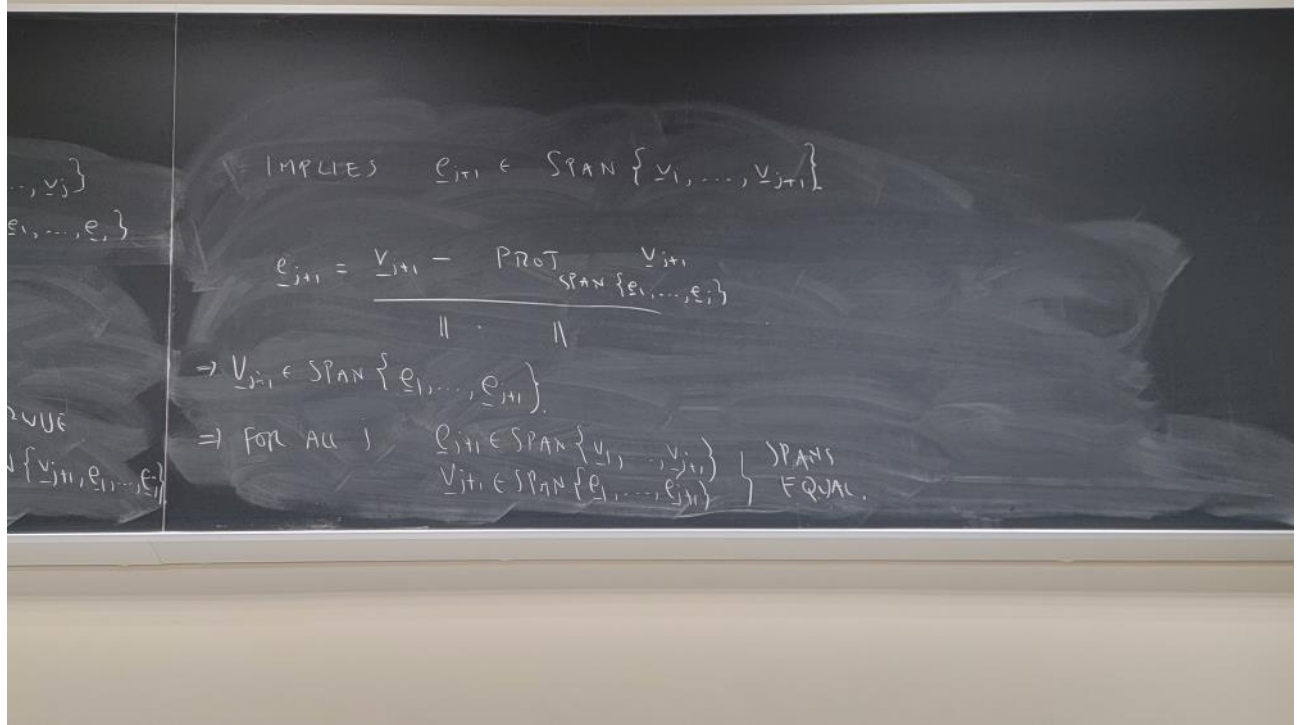
CLAIM. ① $\text{SPAN}\{\underline{v}_1, \dots, \underline{v}_j\} = \text{SPAN}\{\underline{e}_1, \dots, \underline{e}_j\}$

EACH j .

② $\|\underline{e}_i\| = 1$ ALL i .

③ $\underline{e}_i \cdot \underline{e}_j = \begin{cases} 1 & i=j \\ 0 & \text{OTHERWISE} \end{cases}$

BY CONSTRUCTION, $\underline{e}_{j+1} \in \text{SPAN}\{\underline{v}_{j+1}, \underline{e}_1, \dots, \underline{e}_j\}$
 $\text{SPAN}\{\underline{e}_1, \dots, \underline{e}_j\} = \text{SPAN}\{\underline{v}_1, \dots, \underline{v}_j\}$



ASSUME e_1, \dots, e_{j-1} ORTHONORMAL

$$\begin{aligned} \underline{e}_j \cdot \underline{e}_i &= \frac{1}{\|\cdot\|} \left[\underline{v}_j - (\underline{v}_j \cdot \underline{e}_1) \underline{e}_1 + \dots + (\underline{v}_j \cdot \underline{e}_{j-1}) \underline{e}_{j-1} \right] \cdot \underline{e}_i \\ &= \frac{1}{\|\cdot\|} (\underline{v}_j \cdot \underline{e}_i - (\underline{v}_j \cdot \underline{e}_i)) = 0 \quad \checkmark \quad \underline{e}_i \cdot \underline{e}_i = \begin{cases} 1 & i=j \\ 0 & \text{---} \end{cases} \end{aligned}$$

PROOF IS BY INDUCTION

THE QR FACTORIZATION:

$$M = \begin{bmatrix} | & | & | \\ \underline{v}_1 & \underline{v}_2 & \dots & \underline{v}_m \\ | & | & | \end{bmatrix} = \begin{bmatrix} | & | & | \\ \underline{e}_1 & \underline{e}_2 & \dots & \underline{e}_n \\ | & | & | \end{bmatrix} R$$

$\underline{e}_1, \dots, \underline{e}_n$ ORTHONORMAL Q

\underline{v}_j IS A COMBINATION OF $\underline{e}_1, \dots, \underline{e}_j$.

VIEW R AS FORMING LINEAR COMBINATIONS OF COLUMNS, UPPER TRIANGULAR.

CASE $n=m$.

$$M = \begin{pmatrix} | & & | \\ v_1 & \dots & v_n \\ | & & | \end{pmatrix}$$

IS INVERTIBLE
SINCE COLUMNS LI, SPAN.

$$M = K \begin{pmatrix} \|v_1\| & & 0 \\ & \|v_2\| & \\ 0 & & \ddots \\ & & & \|v_n\| \end{pmatrix} \begin{pmatrix} 1 & & * \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$$

ORTHOGONAL K A DIAGONAL N NILPOTENT,

KAN OR
Iwasawa DECOMPOSITION.

DEFINITION: $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ A LINEAR MAP

IS ORTHOGONAL IF $\|Tx\| = \|x\|$ ALL $x \in \mathbb{R}^n$.

THE MATRIX A , $Tx = Ax$ IS AN ORTHOGONAL MATRIX.

$$\|x+y\|^2 = \|T(x+y)\|^2 = (Tx+Ty) \cdot (Tx+Ty) = \|Tx\|^2 + \|Ty\|^2 + 2Tx \cdot Ty$$
$$\|x\|^2 + \|y\|^2 + 2x \cdot y$$
$$Tx \cdot Ty = x \cdot y$$

(PRESERVES LENGTHS AND ANGLES)

TWO TYPES OF ORTHOG 2×2 MATRICES
ROTATIONS AND REFLECTIONS.

$$A = \begin{pmatrix} | & | \\ T e_1 & T e_2 \\ | & | \end{pmatrix}$$

$$\|T e_i\| = 1$$

$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$
$$\begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}$$



ROTATION BY θ .

REFLECTION IN LINE AT $\theta/2$.

THEOREM: (1) $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ IS ORTHOGONAL IFF

$T e_1, \dots, T e_n$ FORM AN ORTHONORMAL BASIS.

(2) A non ORTHOG \Leftrightarrow COLUMNS ARE AN ORTHONORMAL BASIS.

PROOF: T PRESERVES DOT PRODUCT $T e_i \cdot T e_j = e_i \cdot e_j = \begin{cases} 1 & (i=j) \\ 0 & \text{OTHERWISE,} \end{cases}$

$$A = \begin{pmatrix} | & | & & | \\ T_{e_1} & T_{e_2} & \dots & T_{e_n} \\ | & | & & | \end{pmatrix}$$

Ex: $A = \frac{1}{2} \begin{bmatrix} 1 & 1 & -1 & -1 \\ 1 & -1 & 1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix}$

THEOREM: A, B ORTHOGONAL, A · B ORTHOGONAL
 A ORTHOGONAL → A⁻¹ ORTHOGONAL

PROOF: $\|Ax\|^2 = \|x\|^2 = \|x\|^2$
 $\|Ax\| = \|x\| \Leftrightarrow \|A^{-1}y\| = \|y\| \quad y = Ax \quad \checkmark$